

INTELLIGENT SYSTEMS (CSE-303-F) Section B Dealing with Uncertainty

Introduction

- □ The world is not a well-defined place.
- □ There is uncertainty in the facts we know:
 - What's the temperature? Imprecise measures
 - Is Bush a good president? Imprecise definitions
 - Where is the pit? Imprecise knowledge
- There is uncertainty in our inferences
 - If I have a blistery, itchy rash and was gardening all weekend I probably have poison ivy
- People make successful decisions all the time anyhow.

Sources of Uncertainty

Uncertain data

 missing data, unreliable, ambiguous, imprecise representation, inconsistent, subjective, derived from defaults, noisy...

Uncertain knowledge

- Multiple causes lead to multiple effects
- Incomplete knowledge of causality in the domain
- Probabilistic/stochastic effects
- Uncertain knowledge representation
 - restricted model of the real system
 - Iimited expressiveness of the representation mechanism
- □ inference process
 - Derived result is formally correct, but wrong in the real world
 - New conclusions are not well-founded (eg, inductive reasoning)
 - Incomplete, default reasoning methods

Reasoning Under Uncertainty

So how do we do reasoning under uncertainty and with inexact knowledge?

- heuristics
 - ways to mimic heuristic knowledge processing methods used by experts
- empirical associations
 - experiential reasoning
 - based on limited observations
- probabilities
 - objective (frequency counting)
 - subjective (human experience)

Decision making with uncertainty

Rational behavior:

- For each possible action, identify the possible outcomes
- Compute the probability of each outcome
- Compute the utility of each outcome
- Compute the probability-weighted (expected) utility over possible outcomes for each action
- Select the action with the highest expected utility (principle of Maximum Expected Utility)

Some Relevant Factors

expressiveness

- can concepts used by humans be represented adequately?
- can the confidence of experts in their decisions be expressed?

comprehensibility

- representation of uncertainty
- utilization in reasoning methods

correctness

- probabilities
- relevance ranking
- Iong inference chains
- computational complexity
 - feasibility of calculations for practical purposes
- reproducibility
 - will observations deliver the same results when repeated?

Basics of Probability Theory

- mathematical approach for processing uncertain information
 - sample space set
 - $X = \{x1, x2, ..., xn\}$
 - collection of all possible events
 - can be discrete or continuous
 - probability number P(xi): likelihood of an event xi to occur
 - non-negative value in [0,1]
 - total probability of the sample space is 1
 - for mutually exclusive events, the probability for at least one of them is the sum of their individual probabilities
 - experimental probability
 - based on the frequency of events
 - subjective probability
 - based on expert assessment

Compound Probabilities

 describes *independent* events
 do not affect each other in any way
 joint probability of two independent events A and B P(A ∩ B) = P(A) * P (B)
 union probability of two independent events A and

B

 $P(A \cup B) = P(A) + P(B) - P(A \cap B)$ =P(A) + P(B) - P(A) * P(B)

Probability theory

- Random variables
 - Domain
- Atomic event: complete specification of state
- Prior probability: degree of belief without any other evidence
- Joint probability: matrix of combined probabilities of a set of variables

□ Alarm, Burglary, Earthquake

- Boolean (like these), discrete, continuous
- Alarm=True Alary=True
 Aarthquake=False
 alarm burglary earthquake

 \Box P(Burglary) = .1

 \Box P(Alarm, Burglary) =

	alarm	¬alarm
burglary	.09	.01
¬burglary	.1	.8

Probability theory (cont.)

- Conditional probability: probability of effect given causes
- Computing conditional probs:
 - P(a | b) = P(a ^ b) / P(b)
 - P(b): normalizing constant
- Product rule:
 - P(a ∧ b) = P(a | b) P(b)
- □ Marginalizing:
 - $P(B) = \Sigma_a P(B, a)$
 - P(B) = Σ_aP(B | a) P(a) (conditioning)

P(burglary | alarm) = .47
 P(alarm | burglary) = .9

- P(burglary | alarm) =
 P(burglary \wedge alarm) / P(alarm)
 = .09 / .19 = .47
- P(burglary \wedge alarm) =
 P(burglary | alarm) P(alarm) =
 .47 * .19 = .09
- □ P(alarm) = P(alarm \land burglary) + P(alarm \land ¬burglary) = .09+.1 = .19

Independence

When two sets of propositions do not affect each others' probabilities, we call them **independent**, and can easily compute their joint and conditional probability:

Independent (A, B) if $P(A \land B) = P(A) P(B)$, $P(A \mid B) = P(A)$

- For example, {moon-phase, light-level} might be independent of {burglary, alarm, earthquake}
 - Then again, it might not: Burglars might be more likely to burglarize houses when there's a new moon (and hence little light)
 - But if we know the light level, the moon phase doesn't affect whether we are burglarized
 - Once we're burglarized, light level doesn't affect whether the alarm goes off
- We need a more complex notion of independence, and methods for reasoning about these kinds of relationships

Exercise: Independence

p(smart ∧ study ∧ prep)	smart		–smart	
	study	-study	study	study
prepared	.432	.16	.084	.008
-prepared	.048	.16	.036	.072

Queries:

Is *smart* independent of *study*?
Is *prepared* independent of *study*?

Conditional independence

□Absolute independence:

A and B are independent if P(A \wedge B) = P(A) P(B); equivalently, P(A) = P(A | B) and P(B) = P(B | A)

□A and B are **conditionally independent** given C if

 $\blacksquare P(A \land B | C) = P(A | C) P(B | C)$

□This lets us decompose the joint distribution:

 $\blacksquare P(A \land B \land C) = P(A | C) P(B | C) P(C)$

Moon-Phase and Burglary are conditionally independent given Light-Level

Conditional independence is weaker than absolute independence, but still useful in decomposing the full joint probability distribution

Exercise: Conditional independence

p(smart ∧ study ∧ prep)	smart		smart	
	study	-study	study	⊣study
prepared	.432	.16	.084	.008
-prepared	.048	.16	.036	.072

Queries:

- Is smart conditionally independent of prepared, given study?
- Is study conditionally independent of prepared, given smart?

Conditional Probabilities

 describes *dependent* events
 affect each other in some way
 conditional probability of event a given that event B has already occurred P(A|B) = P(A ∩ B) / P(B)

Bayesian Approaches

derive the probability of an event given another event
 Often useful for diagnosis:

- If X are (observed) effects and Y are (hidden) causes,
- We may have a model for how causes lead to effects (P(X | Y))
- We may also have prior beliefs (based on experience) about the frequency of occurrence of effects (P(Y))
- Which allows us to reason abductively from effects to causes (P(Y | X)).

has gained importance recently due to advances in efficiency

- more computational power available
- better methods

Bayes' Rule for Single Event

single hypothesis H, single event E
P(H|E) = (P(E|H) * P(H)) / P(E)

or

□ P(H|E) = (P(E|H) * P(H) / (P(E|H) * P(H) + P(E|¬H) * P(¬H))

Bayes Example: Diagnosing Meningitis

Suppose we know that

- Stiff neck is a symptom in 50% of meningitis cases
- Meningitis (m) occurs in 1/50,000 patients
- Stiff neck (s) occurs in 1/20 patients

□ Then

- P(s|m) = 0.5, P(m) = 1/50000, P(s) = 1/20
- $\bullet P(m|s) = (P(s|m) P(m))/P(s)$

= (0.5 x 1/50000) / 1/20 = .0002

So we expect that one in 5000 patients with a stiff neck to have meningitis.

Advantages and Problems Of Bayesian Reasoning

□ advantages

- sound theoretical foundation
- well-defined semantics for decision making

problems

- requires large amounts of probability data
 sufficient sample sizes
- subjective evidence may not be reliable
- independence of evidences assumption often not valid
- relationship between hypothesis and evidence is reduced to a number
- explanations for the user difficult
- high computational overhead

Some Issues with Probabilities

- Often don't have the data
 - Just don't have enough observations
 - Data can't readily be reduced to numbers or frequencies.
- Human estimates of probabilities are notoriously inaccurate. In particular, often add up to >1.
- □ Doesn't always match human reasoning well.
 - P(x) = 1 P(-x). Having a stiff neck is strong (.9998!) evidence that you don't have meningitis. True, but counterintuitive.

Several other approaches for uncertainty address some of these problems.

Dempster-Shafer Theory

- mathematical theory of evidence
- □ Notations
 - Environment T: set of objects that are of interest
 - frame of discernment FD
 - power set of the set of possible elements
 - mass probability function m
 - assigns a value from [0,1] to every item in the frame of discernment
 - mass probability m(A)
 portion of the total mass probability that is assigned to an element A of FD

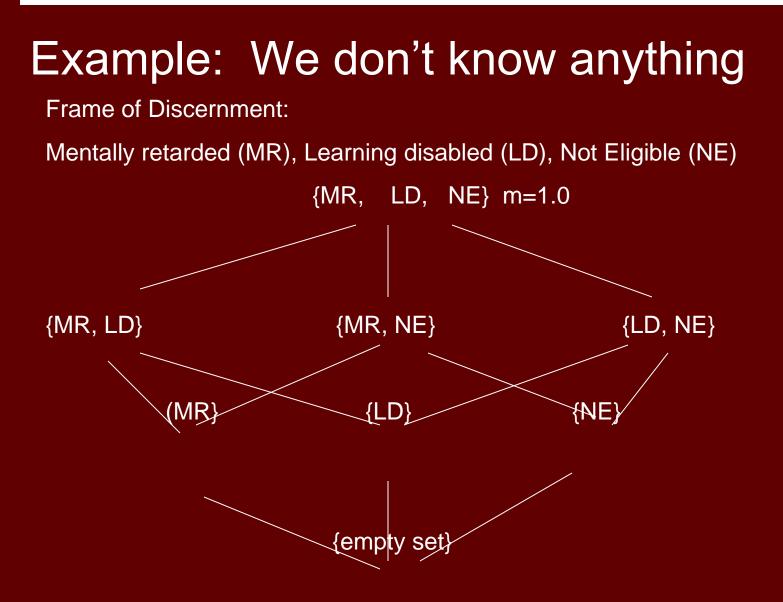
D-S Underlying concept

- □ The most basic problem with uncertainty is often with the axiom that P(X) +P(not X) = 1
 - If the probability that you have poison ivy when you have a rash is .3, this means that a rash is strongly suggestive (.7) that you don't have poison ivy.
 - True, in a sense, but neither intuitive nor helpful.
- What you really mean is that the probability is .3 that you have poison ivy and .7 that we don't know yet what you have.
- □ So we initially assign all of the probability to the total set of things you *might* have: the frame of discernment.

Example: Frame of Discernment

Environment: Mentally retarded (MR), Learning disabled (LD), Not Eligible (NE)

 $\{MR, LD, NE\}$ $\{MR, LD\}$ {MR, NE} $\{LD, NE\}$ $\{LD\}$ (MR} $\{NE\}$ {empty set}

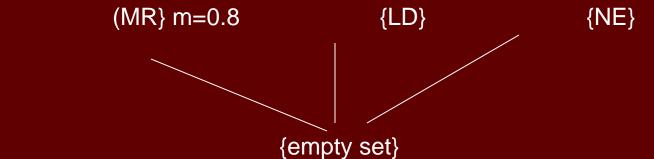


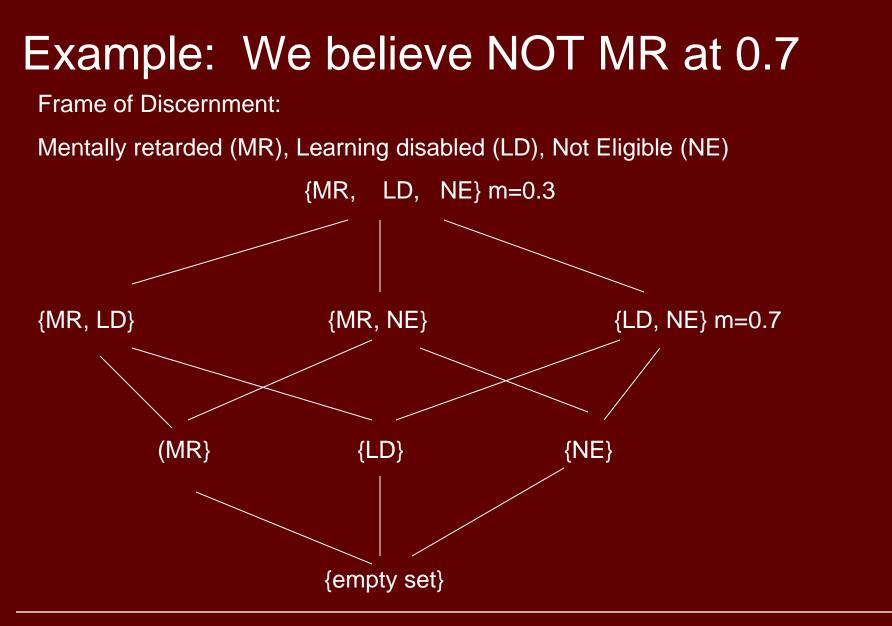
Example: We believe MR at 0.8

Frame of Discernment:

Mentally retarded (MR), Learning disabled (LD), Not Eligible (NE)

{MR, LD, NE} m=0.2 {MR, LD} {MR, NE} {LD, NE}





Belief and Certainty

belief Bel(A) in a subset A

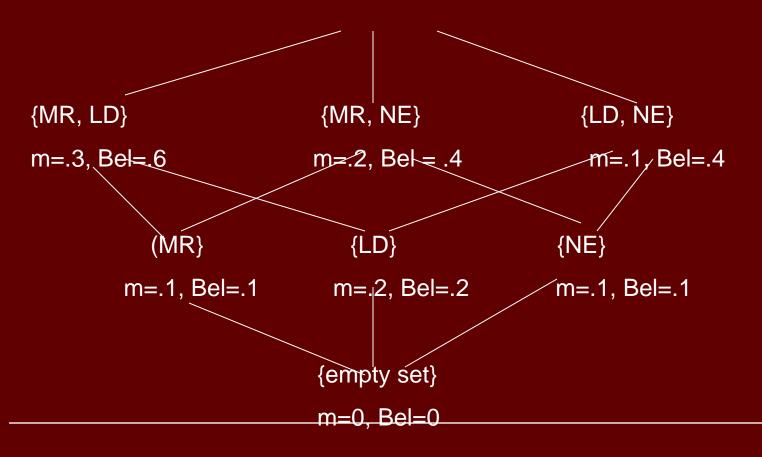
- sum of the mass probabilities of all the proper subsets of A
- likelihood that one of its members is the conclusion
- □ plausibility Pls(A)
 - maximum belief of A, upper bound
 - 1 Bel(not A)
- certainty Cer(A)
 - interval [Bel(A), Pls(A)]
 - expresses the range of belief

Example: Bel, Pls

Frame of Discernment:

Mentally retarded (MR), Learning disabled (LD), Not Eligible (NE)

{MR, LD, NE} m=0, Bel=1



Interpretation: Some Evidential Intervals

- □ Completely true: [1,1]
- □ Completely false: [0,0]
- □ Completely ignorant: [0,1]
- \Box Doubt -- disbelief in X: Dbt = Bel(not X)
- □ Ignorance -- range of uncertainty: Igr =PIs-Bel
- □ Tends to support: [Bel, 1] (0<Bel<1)
- □ Tends to refute: [0, PIs] (0>PIs<1)
- Tends to both support and refute: [Bel, Pls] (0<Bel<Pls<1)</p>

Advantages and Problems of Dempster-Shafer

advantages

- clear, rigorous foundation
- ability to express confidence through intervals
 certainty about certainty

problems

- non-intuitive determination of mass probability
- very high computational overhead
- may produce counterintuitive results due to normalization when probabilities are combined
- Still hard to get numbers

Certainty Factors

- shares some foundations with Dempster-Shafer theory, but more practical
- denotes the belief in a hypothesis H given that some pieces of evidence are observed
- no statements about the belief is no evidence is present
 - in contrast to Bayes' method

Belief and Disbelief

measure of belief

- degree to which hypothesis H is supported by evidence E
- MB(H,E) = 1 IF P(H) =1 (P(H|E) - P(H)) / (1- P(H)) otherwise

measure of disbelief

- degree to which doubt in hypothesis H is supported by evidence E
- MB(H,E) = 1 IF P(H) =0 (P(H) - P(H|E)) / P(H)) otherwise

Certainty Factor

- certainty factor CF
 - ranges between -1 (denial of the hypothesis H) and 1 (confirmation of H)
- □ CF = (MB MD) / (1 min (MD, MB))

combining antecedent evidence

use of premises with less than absolute confidence
E1 ∧ E2 = min(CF(H, E1), CF(H, E2))
E1 ∨ E2 = max(CF(H, E1), CF(H, E2))
¬E = ¬ CF(H, E)

Combining Certainty Factors

certainty factors that support the same conclusion
 several rules can lead to the same conclusion
 applied incrementally as new evidence becomes available

□ Cfrev(CFold, CFnew) =

- CFold + CFnew(1 CFold) if both > 0
- CFold + CFnew(1 + CFold) if both < 0</p>
- CFold + CFnew / (1 min(|CFold|, |CFnew|)) if one < 0</p>

Advantages of Certainty Factors

□Advantages

- simple implementation
- reasonable modeling of human experts' belief
 expression of belief and disbelief
- successful applications for certain problem classes
- evidence relatively easy to gather
 no statistical base required

Problems of Certainty Factors

Problems

- partially ad hoc approach
 - theoretical foundation through Dempster-Shafer theory was developed later
- combination of non-independent evidence unsatisfactory
- new knowledge may require changes in the certainty factors of existing knowledge
- certainty factors can become the opposite of conditional probabilities for certain cases
- not suitable for long inference chains

Fuzzy Logic

 approach to a formal treatment of uncertainty
 relies on quantifying and reasoning through natural (or at least non-mathematical) language

- Rejects the underlying concept of an excluded middle: things have a degree of membership in a concept or set
 - Are you tall?
 - Are you rich?

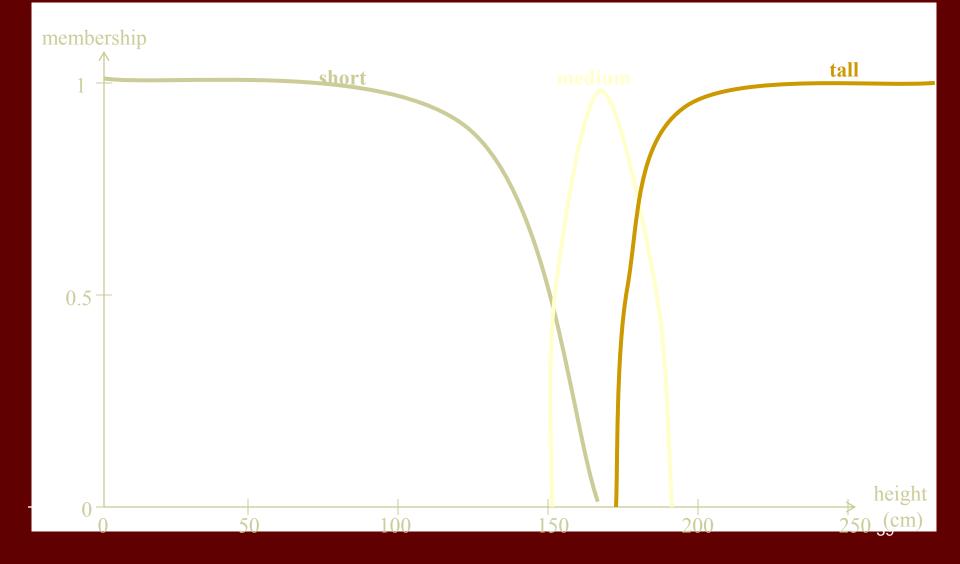
As long as we have a way to formally describe degree of membership and a way to combine degrees of memberships, we can reason.

Fuzzy Set

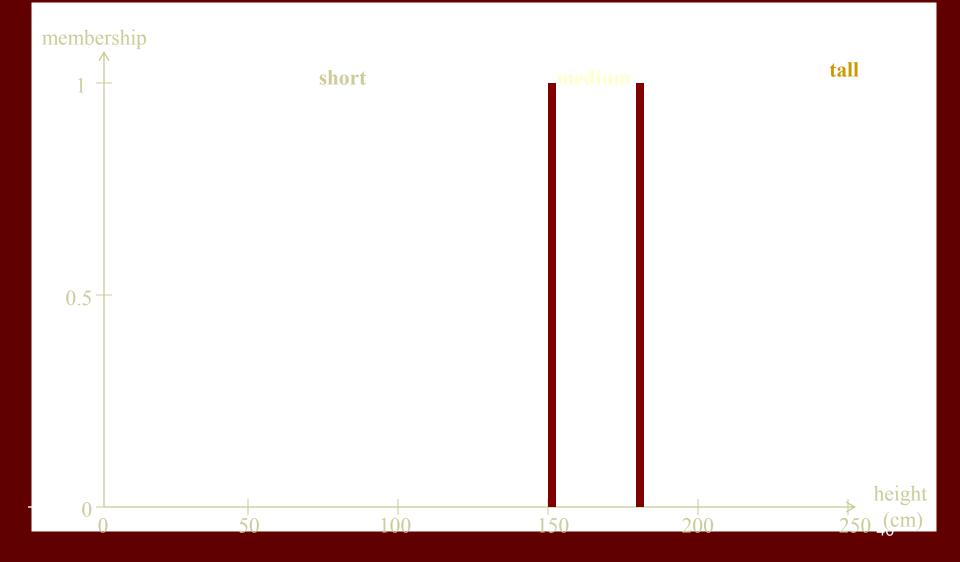
categorization of elements xi into a set S

- described through a membership function m(s)
- associates each element xi with a degree of membership in S
- □ possibility measure Poss{ $x \in S$ }
 - degree to which an individual element x is a potential member in the fuzzy set S
 - combination of multiple premises
 - $\square Poss(A \land B) = min(Poss(A), Poss(B))$
 - $\square Poss(A \lor B) = max(Poss(A), Poss(B))$

Fuzzy Set Example



Fuzzy vs. Crisp Set



Fuzzy Reasoning

- In order to implement a fuzzy reasoning system you need
 - For each variable, a defined set of values for membership
 - Can be numeric (1 to 10)
 - Can be linguistic
 - really no, no, maybe, yes, really yes
 - tiny, small, medium, large, gigantic
 - good, okay, bad
 - And you need a set of rules for combining them
 Good and bad = okay.

Fuzzy Inference Methods

□ Lots of ways to combine evidence across rules

- Poss(B|A) = min(1, (1 Poss(A)+ Poss(B)))
 implication according to Max-Min inference
- also Max-Product inference and other rules
- formal foundation through Lukasiewicz logic
 extension of binary logic to infinite-valued logic
- □ Can be enumerated or calculated.

Some Additional Fuzzy Concepts

- □ Support set: all elements with membership > 0
- Alpha-cut set: all elements with membership greater than alpha
- Height: maximum grade of membership
- Normalized: height = 1
- Some typical domains
- Control (subways, camera focus)
- Pattern Recognition (OCR, video stabilization)
- □ Inference (diagnosis, planning, NLP)

Advantages and Problems of Fuzzy Logic

advantages

- general theory of uncertainty
- wide applicability, many practical applications
- natural use of vague and imprecise concepts
 helpful for commonsense reasoning, explanation

problems

- membership functions can be difficult to find
- multiple ways for combining evidence
- problems with long inference chains

Uncertainty: Conclusions

- In AI we must often represent and reason about uncertain information
- □ This is no different from what people do all the time!
- □ There are multiple approaches to handling uncertainty.
- Probabilistic methods are most rigorous but often hard to apply; Bayesian reasoning and Dempster-Shafer extend it to handle problems of independence and ignorance of data
- Fuzzy logic provides an alternate approach which better supports ill-defined or non-numeric domains.
- Empirically, it is often the case that the main need is some way of expressing "maybe". Any system which provides for at least a three-valued logic tends to yield the same decisions.